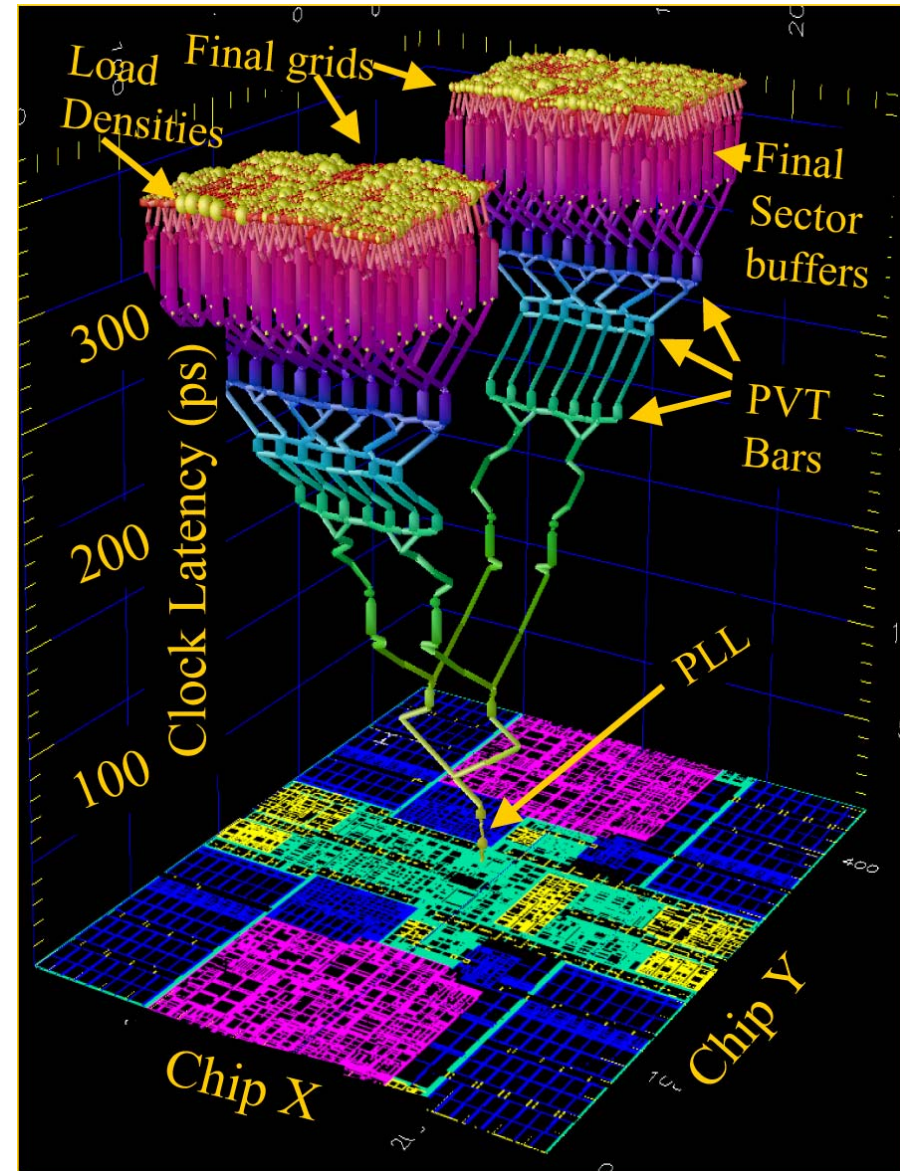


MODULE 7

TIMING DESIGN



Course Material for Timing Design

P	10.1	Introduction	492
I	10.2	Timing Classification	492 – 495
P	10.3.1	Synchronous Timing Basics	495 – 500
I		Clock Jitter	500
I		The combined impact of Skew and Jitter	501 – 502
I	10.3.2	Sources of Skew and Jitter	
I	10.3.3	Clock Distribution Techniques	
O	10.3.4	Latch-Based Clocking	516 – 518
O	10.4-10.7	Self-Timed Circuit Design – Future Directions	519 – 551
P	7.5 – 7.5.1 (!)	Pipelining	358-361

Material from Chapter 10, one section from Chapter 7

Outline

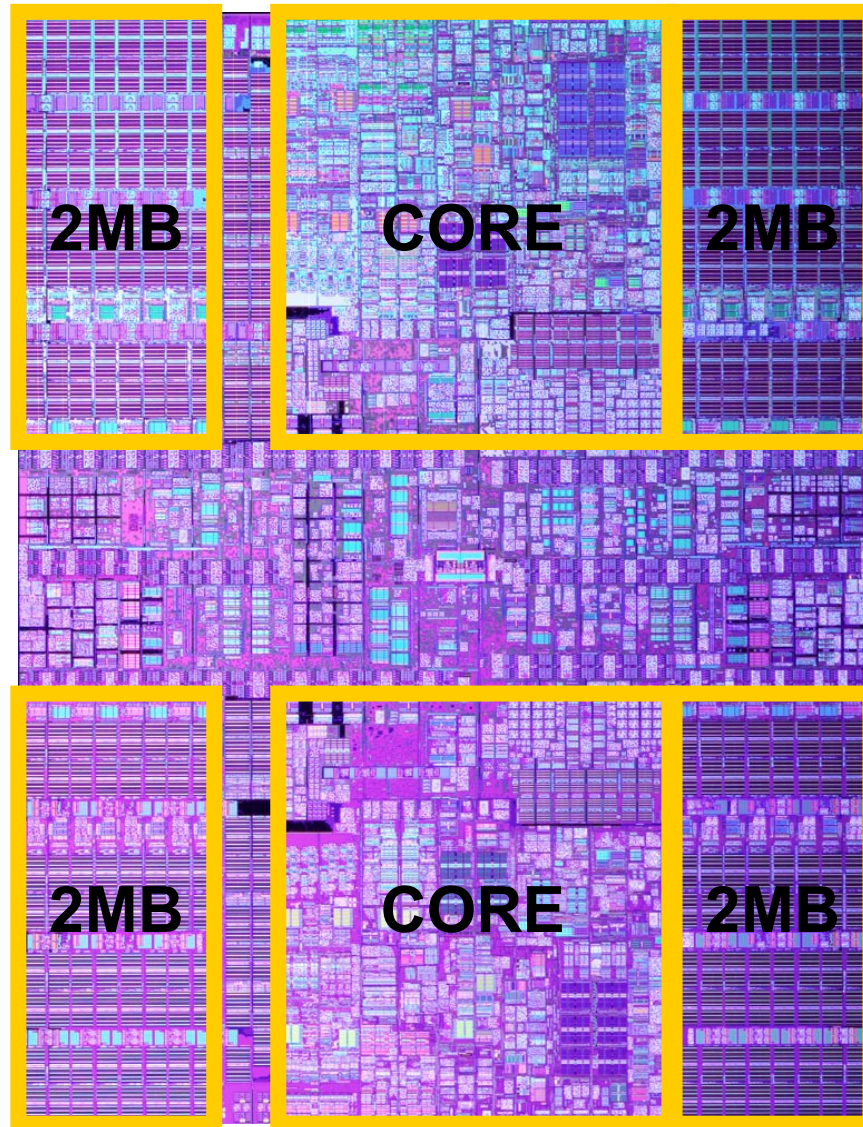
- **Timing Design Background and Motivation**
 - **Delay variations, impact**
 - **Sequential circuits, synchronous design**
 - **Pipelining, metrics reminder**
- **The Clock Skew Problem**
- **Controlling Clock Skew**
- **Case Study**

**Get basic appreciation of some
system level design issues**

Design of LARGE Integrated Circuits

- **Correct signal**
 - **Logic value**
 - **Right level (restoring logic, ...)**
- **At right place**
 - **Interconnect (R, C, L)**
 - **Busses**
 - **Off-chip drivers, and receivers**
- **At right time**
 - **How to cope with (uncertain) delay**

Case Study: IBM Power6 CPU

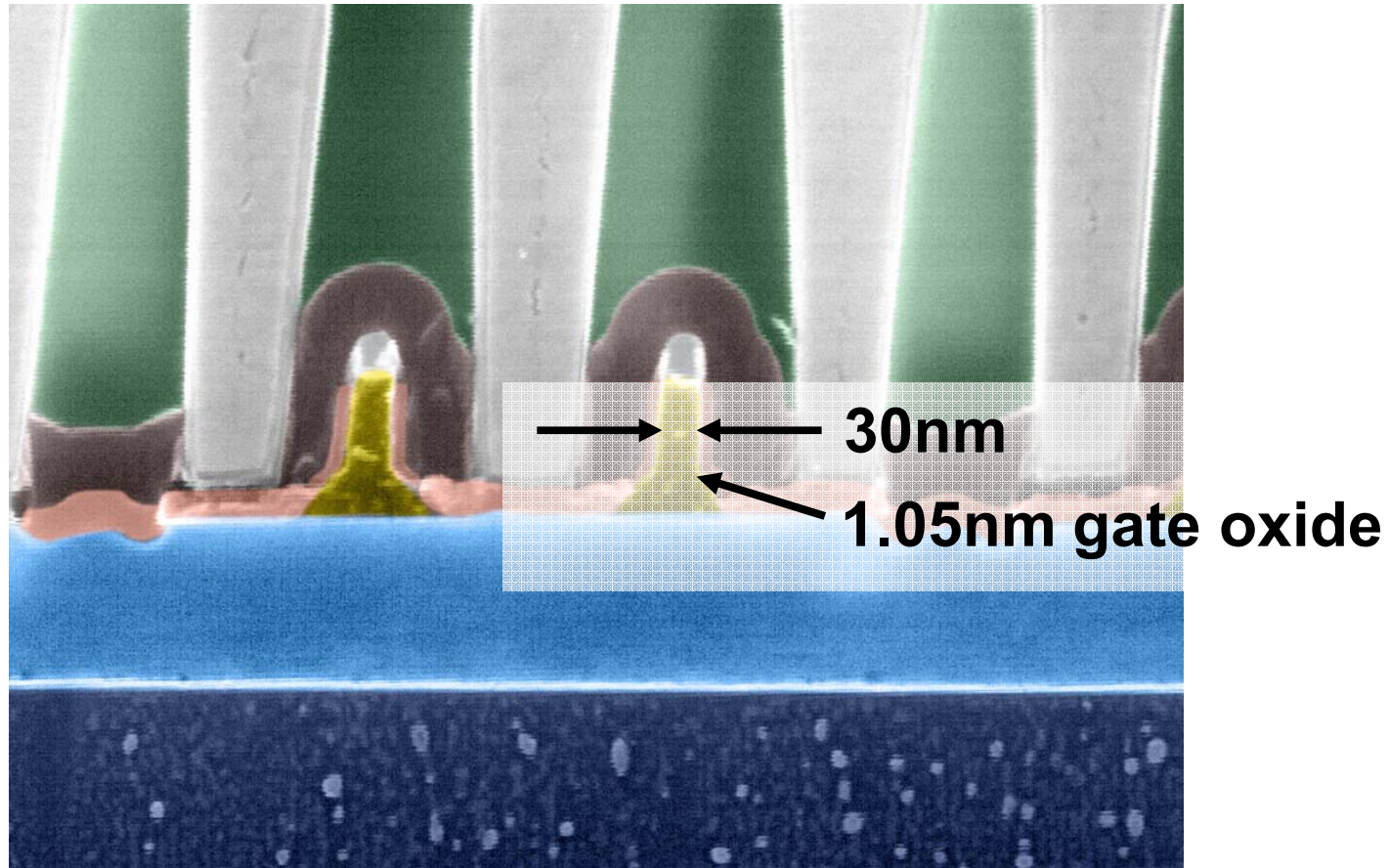


- introduced 21 may 2007
- 64 bit, dual core
- 790 million transistors
- 4.7 (5+) GHz
- 65nm SOI, 10 Cu levels interconnect
- 2 Cores
- 8 MB on-chip level2 cache
- processor bandwidth: 300GB/sec
- 1953 signal I/O, 5449 power I/O

<http://en.wikipedia.org/wiki/POWER6>

<http://www-03.ibm.com/press/us/en/pressrelease/21580.wss>

IBM 65nm SOI Technology

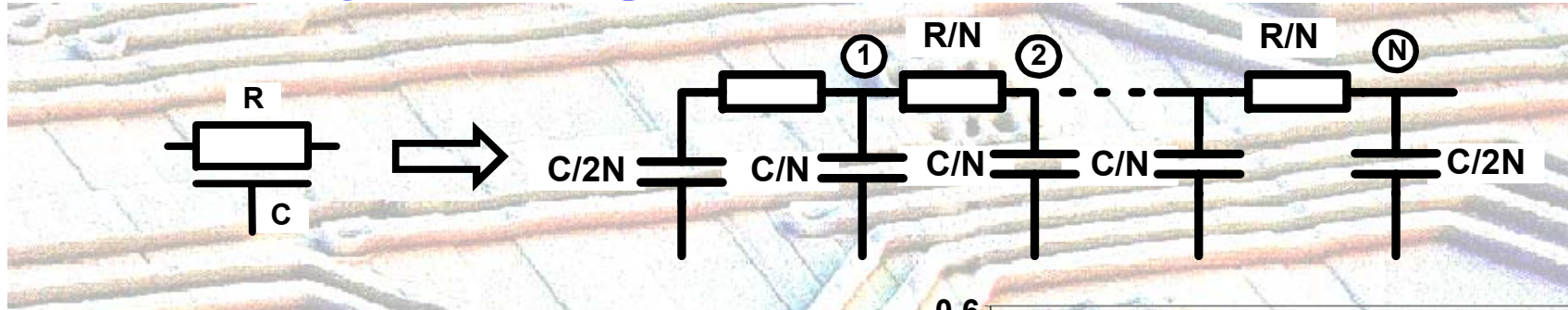


Gate oxide: 1.05 nm ~ 5 atom layers in Si (!!)

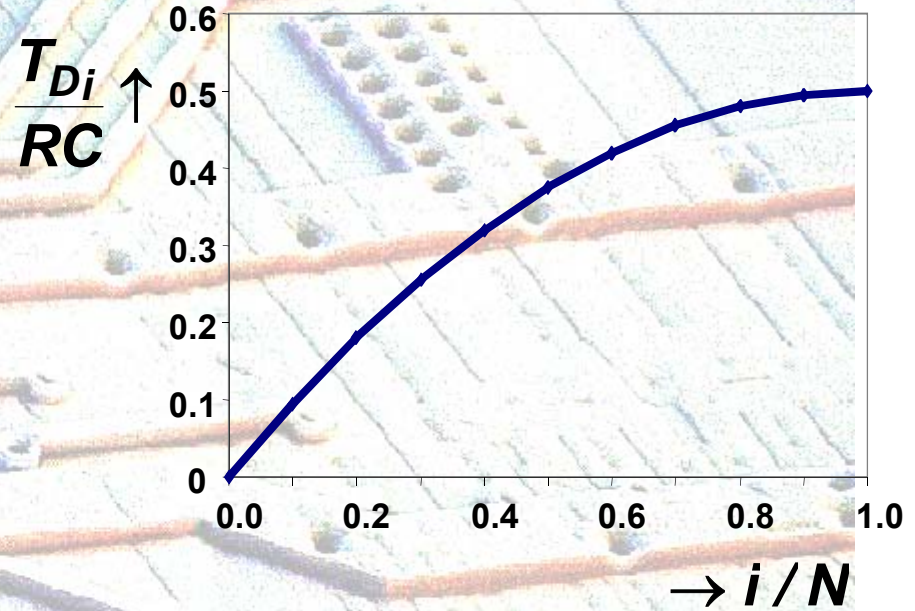
Uncertain Delay

- **Data-dependent Delay**
- **Short and long combinational paths**
- **Device parameters variations (§3.4)**
 - Batch to batch V_t threshold voltage
 - Wafer to wafer k' transconductance
 - Die to die W, L dimensions
- **Supply Variations**
 - IR drop, dl/dt drop, ringing,
- **Interconnect Delay**
 - Don't know length of line during logic design
 - Delay at begin of line smaller than at end
 - Interconnect parameter variability

Delay Along a Wire (Module 3)



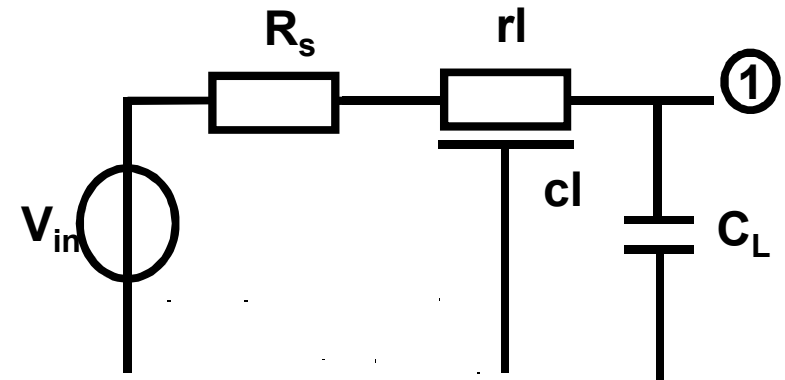
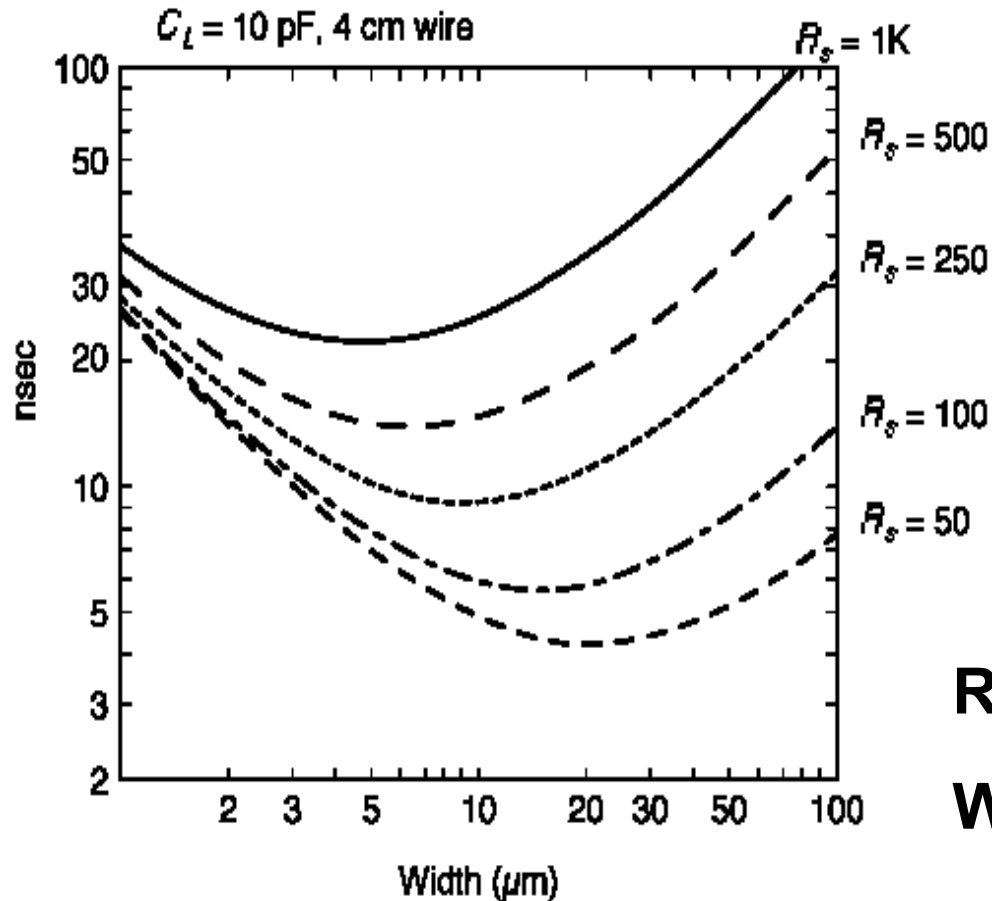
- Signal on RC line exhibits **finite propagation** speed
- **Delay** at beginning of line smaller than at end
- Follows from solving **diffusion equation**
- **Elmore delay model** also predicts propagation behavior (only approximately)



$$T_{Di} = \sum_{k=1}^N R_{ik} C_k$$

■ **Exercise:** draw this graph for $N = 3$, $N = 6$, or use integration to solve limit for $N \rightarrow \infty$

Delay of Clock Wire



$$R = 0.07 \Omega/\square, C = 0.04 \text{ fF}/\mu\text{m}^2$$

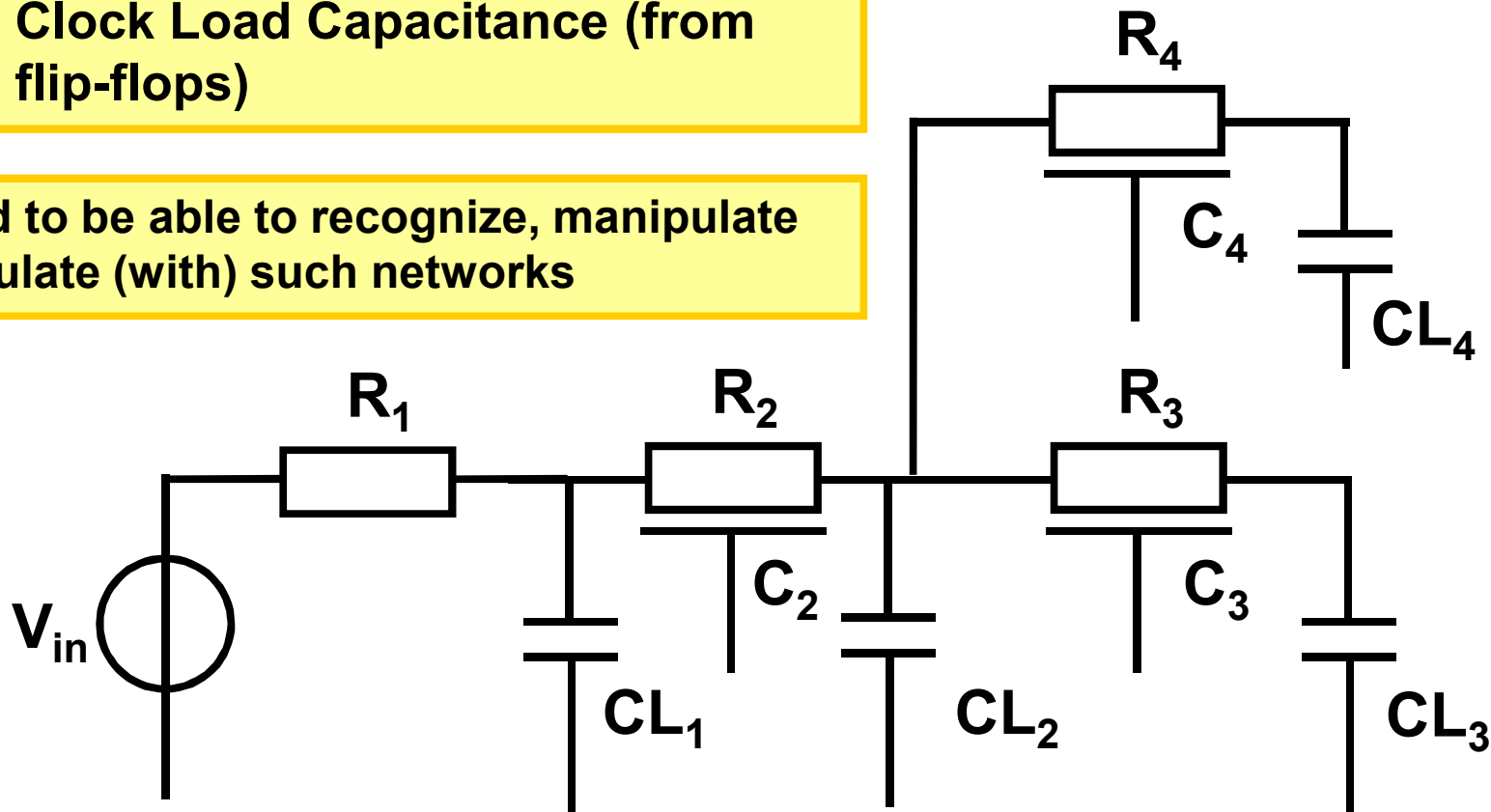
$$W = \text{Width}, r = R/W, c = C \cdot W$$

5ns compares with 200 MHz

Canonical Clock Tree Network

R_1 Clock Driver Output Resistance
 R_2-R_4 Clock Line Segment Resistance
 C_2-C_4 Clock Line Segment Capacitance
 CL_1-CL_4 Clock Load Capacitance (from flip-flops)

You need to be able to recognize, manipulate and calculate (with) such networks



Impact of Uncertain Delay.

- **Combinational circuits** will eventually **settle** at correct output values when inputs are stable
- **Sequential circuits**
 - **Have state**
 - **Must guarantee storing of correct signals at correct time**
 - **Require ordered computations**

Sequential Circuits

- Sequential circuits require **ordered computation**
- Several ways for **imposing ordering**
 - ✓ ■ **Synchronous** (clock)
 - ✗ ■ **Asynchronous** (unstructured)
 - ✗ ■ **Self-timed** (negotiation)

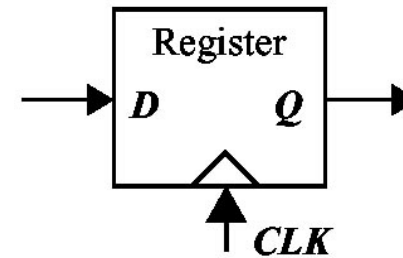
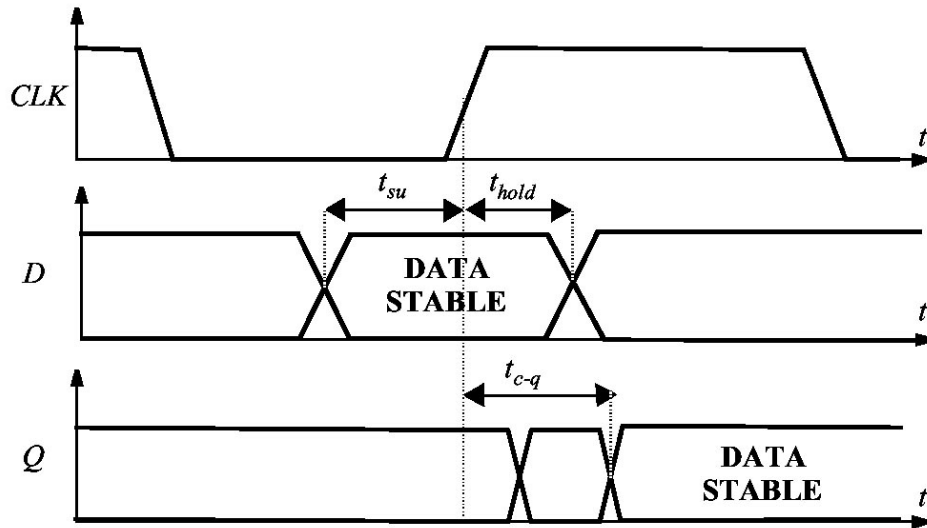
- Clock works like an **orchestra conductor**



Synchronous Design

- **Global Clock Signal**
- **Synchronicity may be defeated by**
 - **Delay uncertainty** in clock signal
 - **Relative timing errors: clock skew**
 - **Slow** logic paths
 - **Fast** logic paths

Timing Metrics Reminder



t_{c-q} : delay from clock (edge) to Q

t_{su} : setup time

t_{hold} : hold time

t_{plogic} : worst case propagation delay of logic

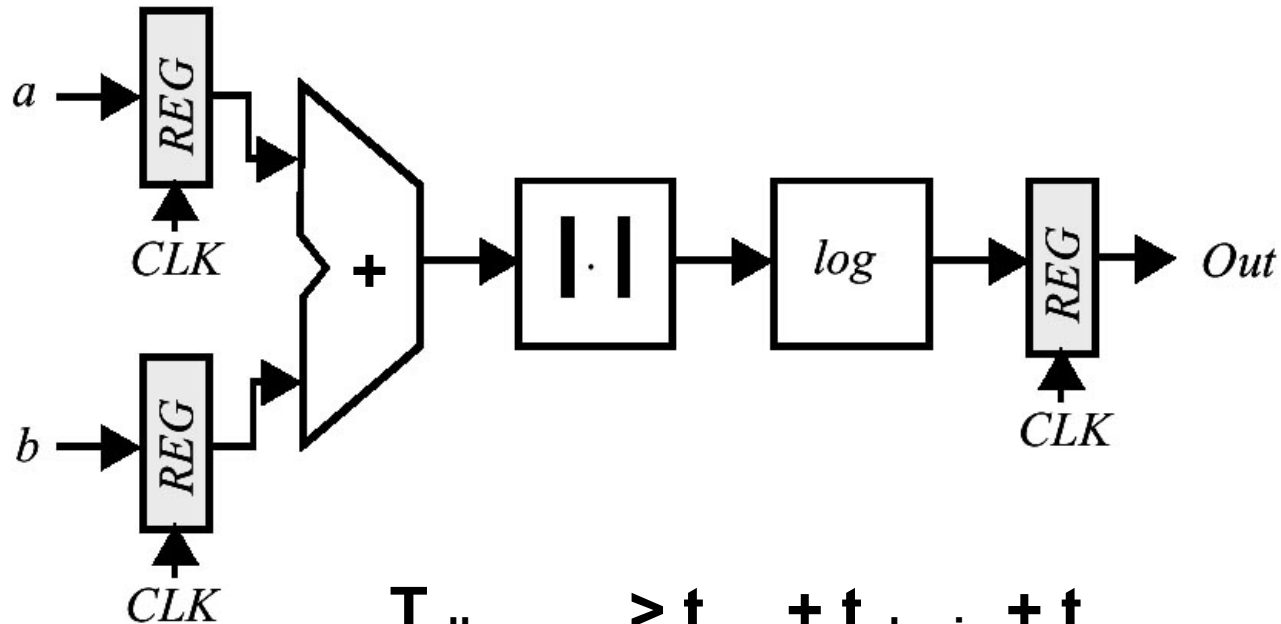
t_{cd} : best case propagation delay
(contamination delay)

T : clock period

$$T \geq t_{c-q} + t_{plogic} + t_{su}$$

$$t_{cdregister} + t_{cdlogic} \geq t_{hold}$$

Sequential Circuit Timing.

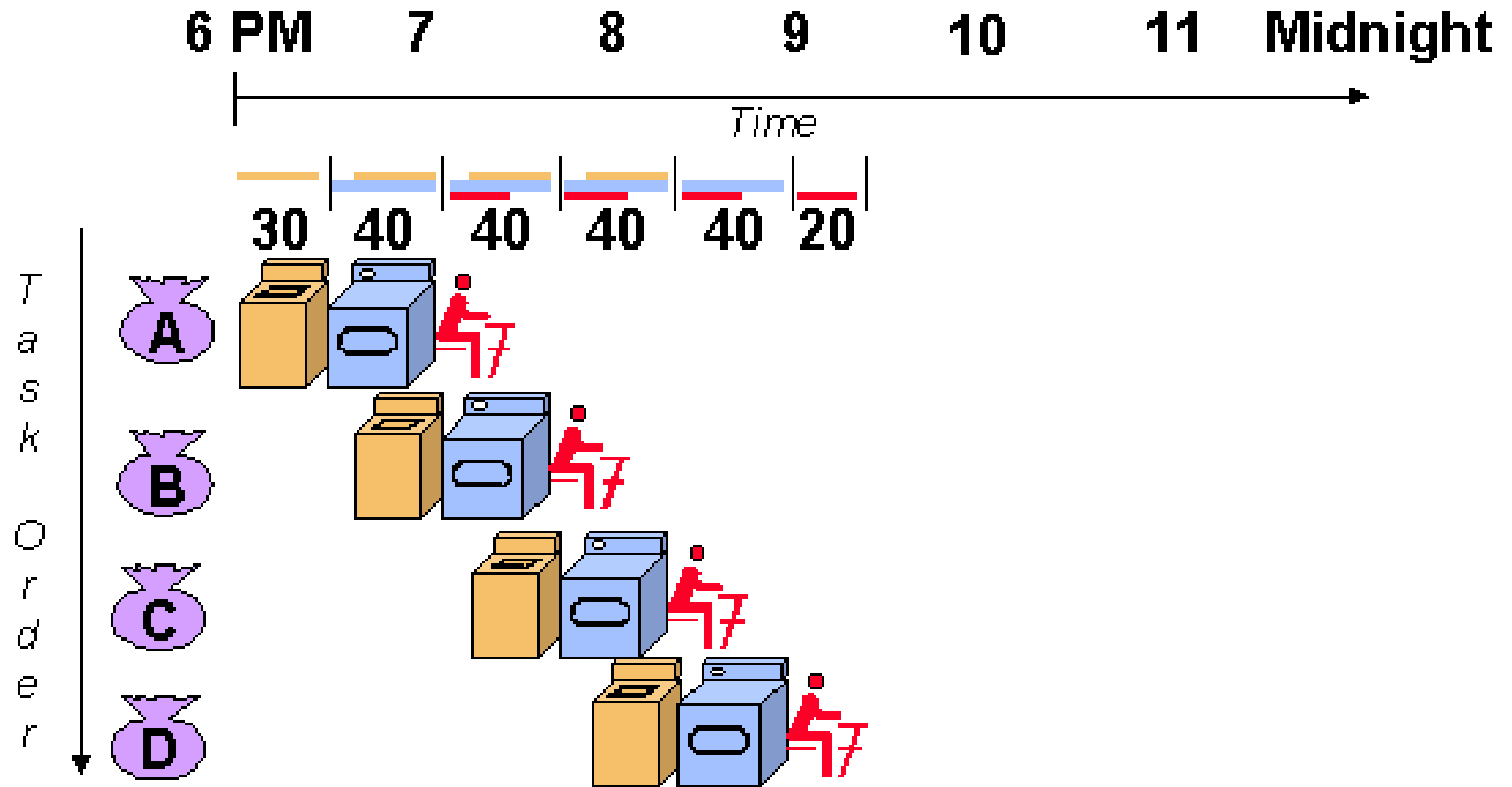


$$T_{\text{clk}} > t_{\text{c-q}} + t_{\text{plogic}} + t_{\text{su}}$$

$$t_{\text{plogic}} = t_{\text{p,add}} + t_{\text{p,abs}} + t_{\text{p,log}}$$

How to reduce T_{clk} ?

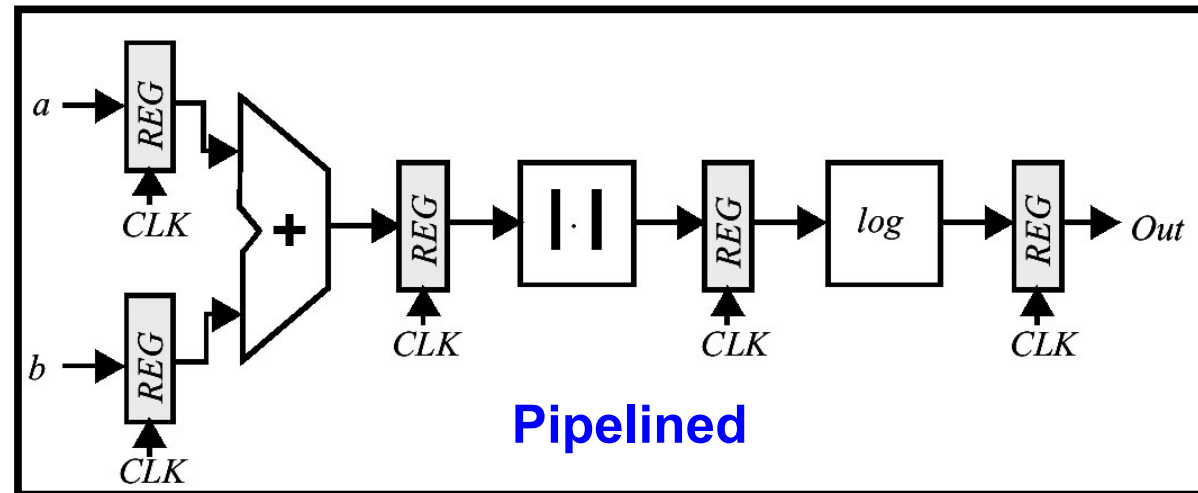
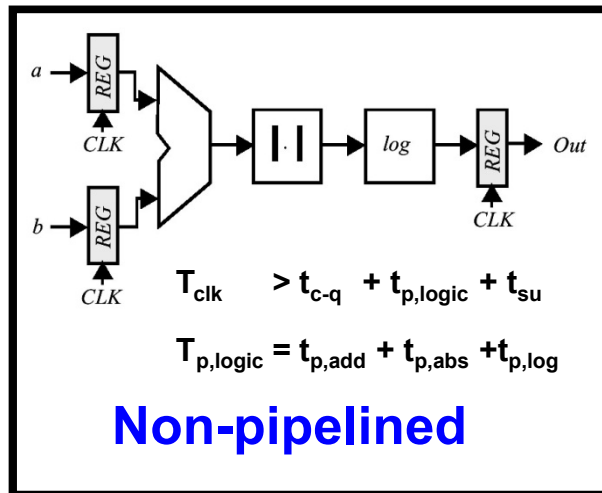
Pipelined Laundry System



Also: <http://en.wikipedia.org/wiki/Pipelining>

From <http://cse.stanford.edu/class/sophomore-college/projects-00/risc/pipelining/index.html>
which credited <http://www.ece.arizona.edu/~ece462/Lec03-pipe/>

Pipelining



Clock Period	Adder	Absolute Value	Logarithm
1	$a_1 + b_1$		
2	$a_2 + b_2$	$ a_1 + b_1 $	
3	$a_3 + b_3$	$ a_2 + b_2 $	$\log(a_1 + b_1)$
4	$a_4 + b_4$	$ a_3 + b_3 $	$\log(a_2 + b_2)$
5	$a_5 + b_5$	$ a_4 + b_4 $	$\log(a_3 + b_3)$



$$T_{clk} > t_{c-q} + \max(t_{p,add}, t_{p,abs}, t_{p,log}) + t_{su}$$

- Improve resource utilization
- Increase functional throughput

Pipelining Observations.

- Very popular/effective measure to increase functional **throughput and resource utilization**
- At the cost of increased **latency**
- All high performance microprocessors excessively use pipelining in **instruction fetch-decode-execute sequence**
- Pipelining efficiency may fall dramatically because of **branches** in program flow
 - Requires emptying of pipeline and **restarting**
 - Partially remedied by **advanced branch prediction techniques**
- But all is dictated by **GHz marketing drive**
 - All a customer asks is: **“How many GHz?”**
 - Or says: **“Mine is ... GHz!”**

Bottom line: more flip-flops, greater timing design problems

The Clock Skew Problem

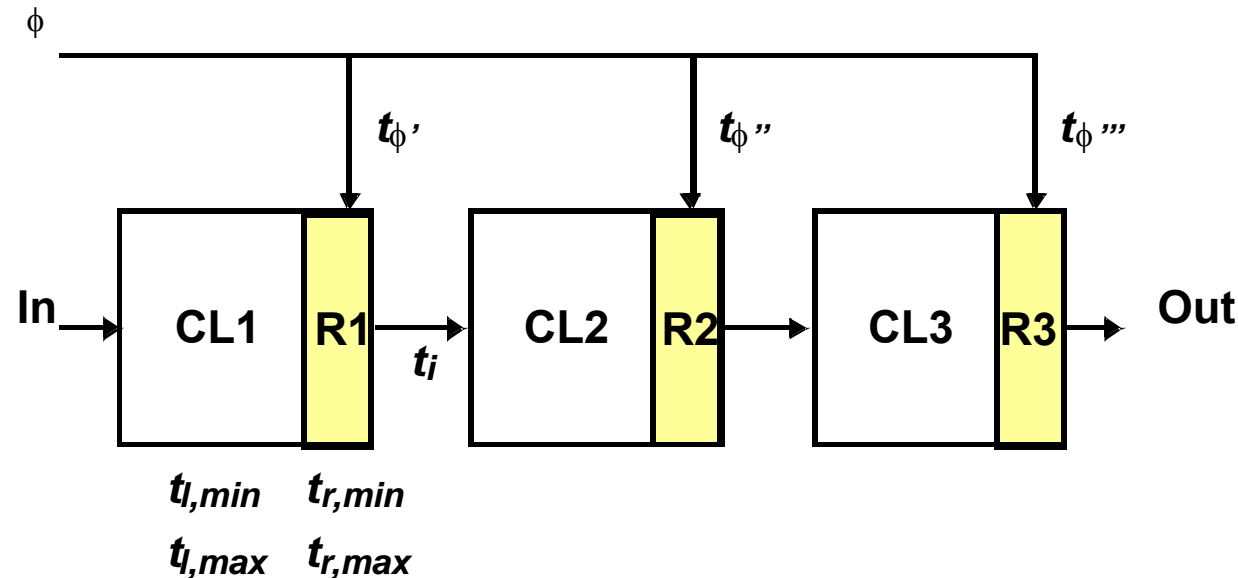
- In Single Phase Edge Triggered Clocking



Brown
§7.15
§10.3.1

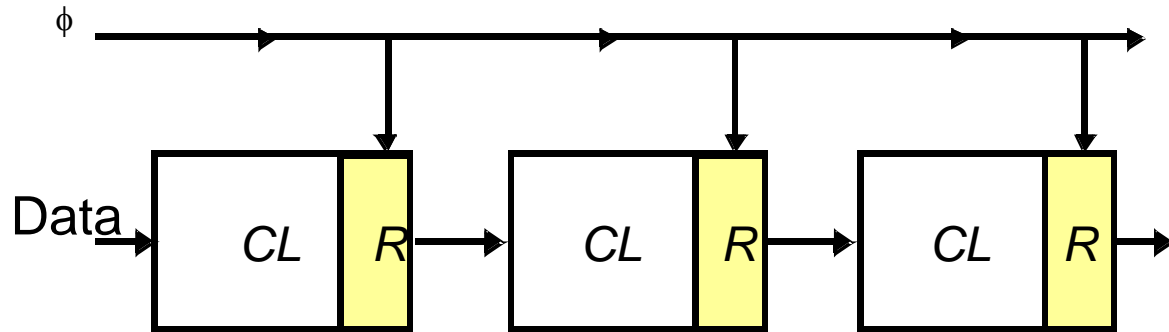
The Clock Skew Problem

Clock Rates \gg 1 Ghz in CMOS

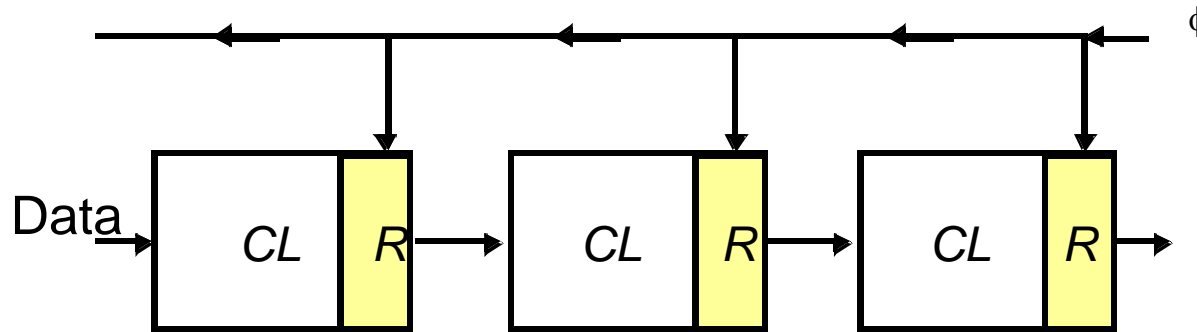


- **Clock Edge Timing Depends upon Position**
 - **Because clock network forms distributed RC line with lumped load capacitances at multiple sites (see earlier slide)**
- **(Relative) Clock Skew $\delta = t_{\phi}''' - t_{\phi}'$**
- **Clock skew can take significant portion of T_{clk}**

Positive and Negative Skew

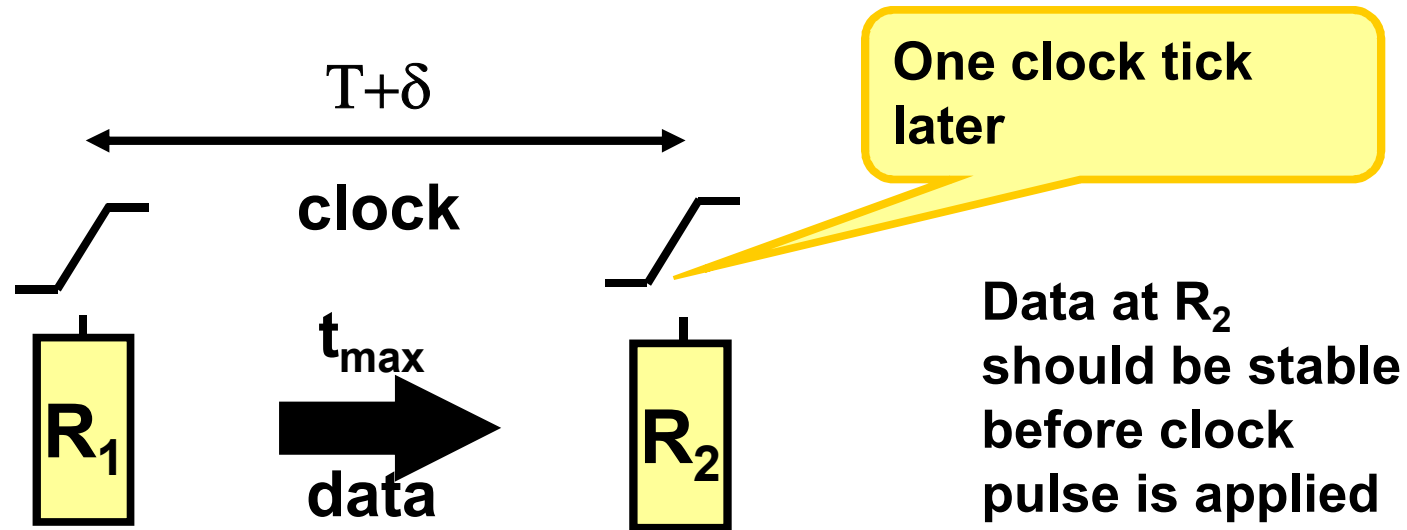


(a) Positive skew



(b) Negative skew

Edge-Triggered Slow Path Skew Constraint



Timing constraint

(t_i = interconnect delay)

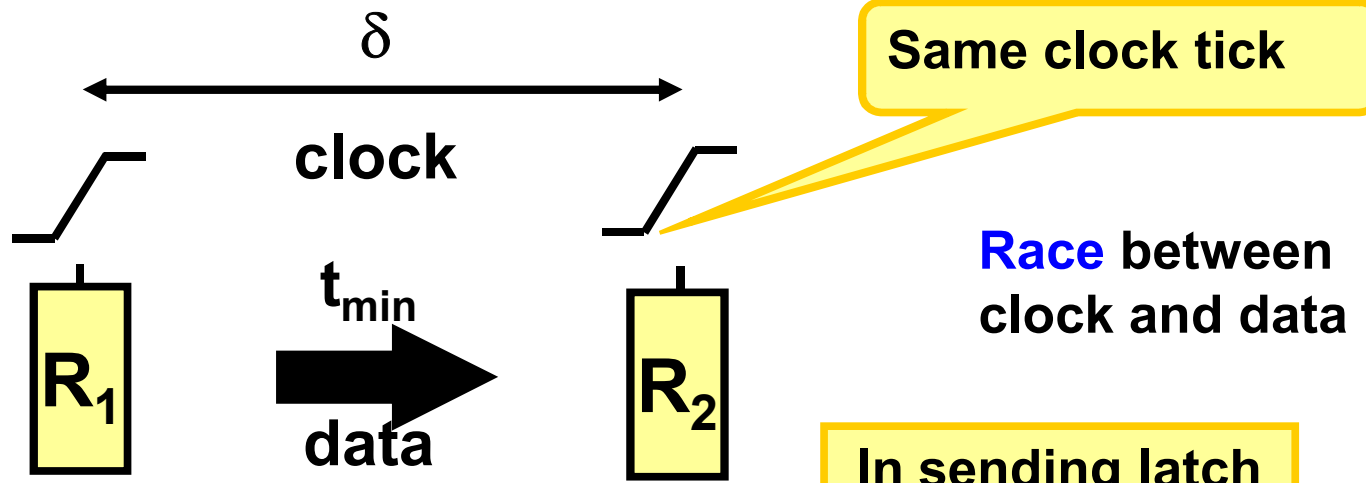
$$T + \delta \geq t_{max} = t_{p,logic} + t_i + t_{c-q,max} + t_{su}$$

Internal delay of flip-flop

$$T \geq t_{max} - \delta$$

- **Minimum Clock Period Determined by Maximum Delay between Latches minus skew**

Edge-Triggered Fast Path Skew Constraint



Timing constraint

$$\delta \leq t_{min} = t_{cd,logic} + t_i + t_{c-q,min} - t_{hold}$$

■ **Maximum Clock Skew Determined by Minimum Delay between Latches**

Clock Constraints in Edge-Triggered Logic.

$$T \geq t_{\max} - \delta$$

$$\delta \leq t_{\min}$$

■ Observe:

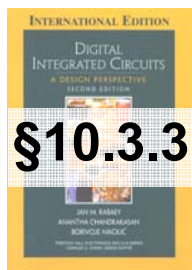
- Minimum Clock Period Determined by Maximum Delay between Registers minus clock skew
- Maximum Clock Skew Determined by Minimum Delay between Registers

■ Conclude:

- Positive skew must be bounded
- Negative skew reduces maximum performance

Controlling Clock Skew

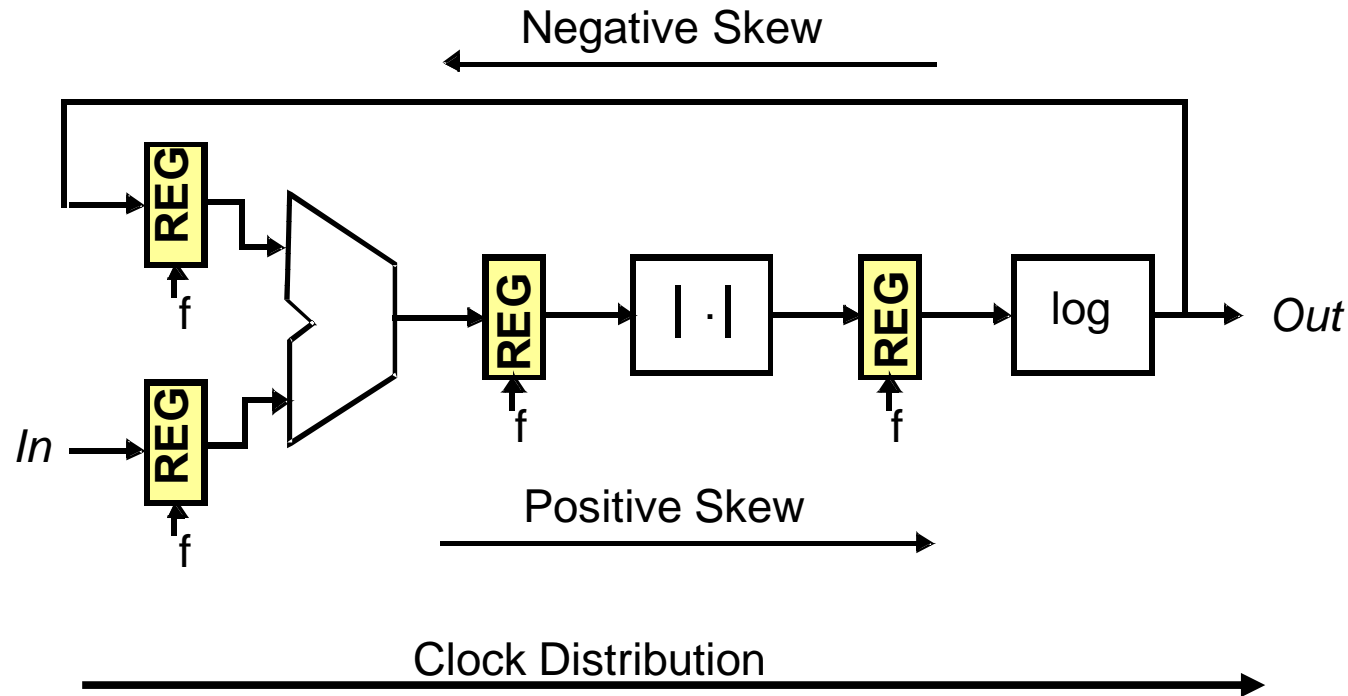
Case Study



Countering Clock Skew Problems

- Routing the clock in **opposite direction** of data (negative skew)
 - Hampers performance
 - Dataflow not always uni-directional
 - Maybe at sub circuit (e.g. datapath) level
 - Other approaches needed at global chip-level
 - Useful skew (or beneficial skew) is serious concept
- Enlarging **non-overlap periods** of clock [only with two-phase clocking]
 - Hampers performance
 - Can theoretically always be made to work
 - Delay in clock network may require impractical/excessively large scheduled $T_{\phi_{12}}$ to guarantee minimum $T_{\phi_{12}}$ everywhere across chip
 - Is becoming less popular for large high performance chips

Dataflow not unidirectional

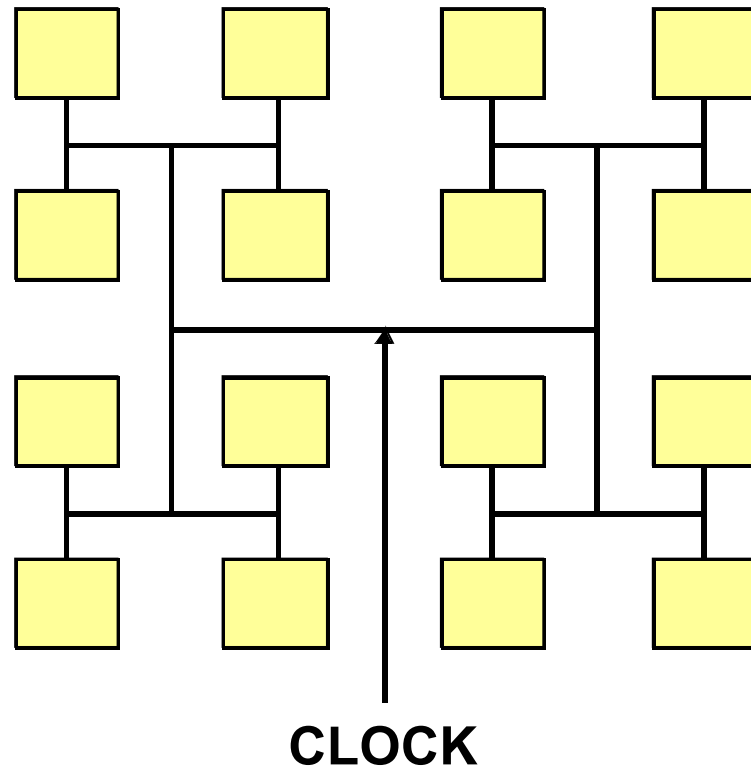


- Data and Clock Routing
- Cannot unambiguously route clock in opposite direction of data
- Need bounded skew

Need bounded Skew

- **Bounded skew most practical measure to guarantee functional correctness without reducing performance**
- **Clock Network Design**
 - **Interconnect material**
 - **Shape of clock-distribution network**
 - **Clock driver, buffers**
 - **Clock-line load**
 - **Clock signal rise and fall times**
 - **...**

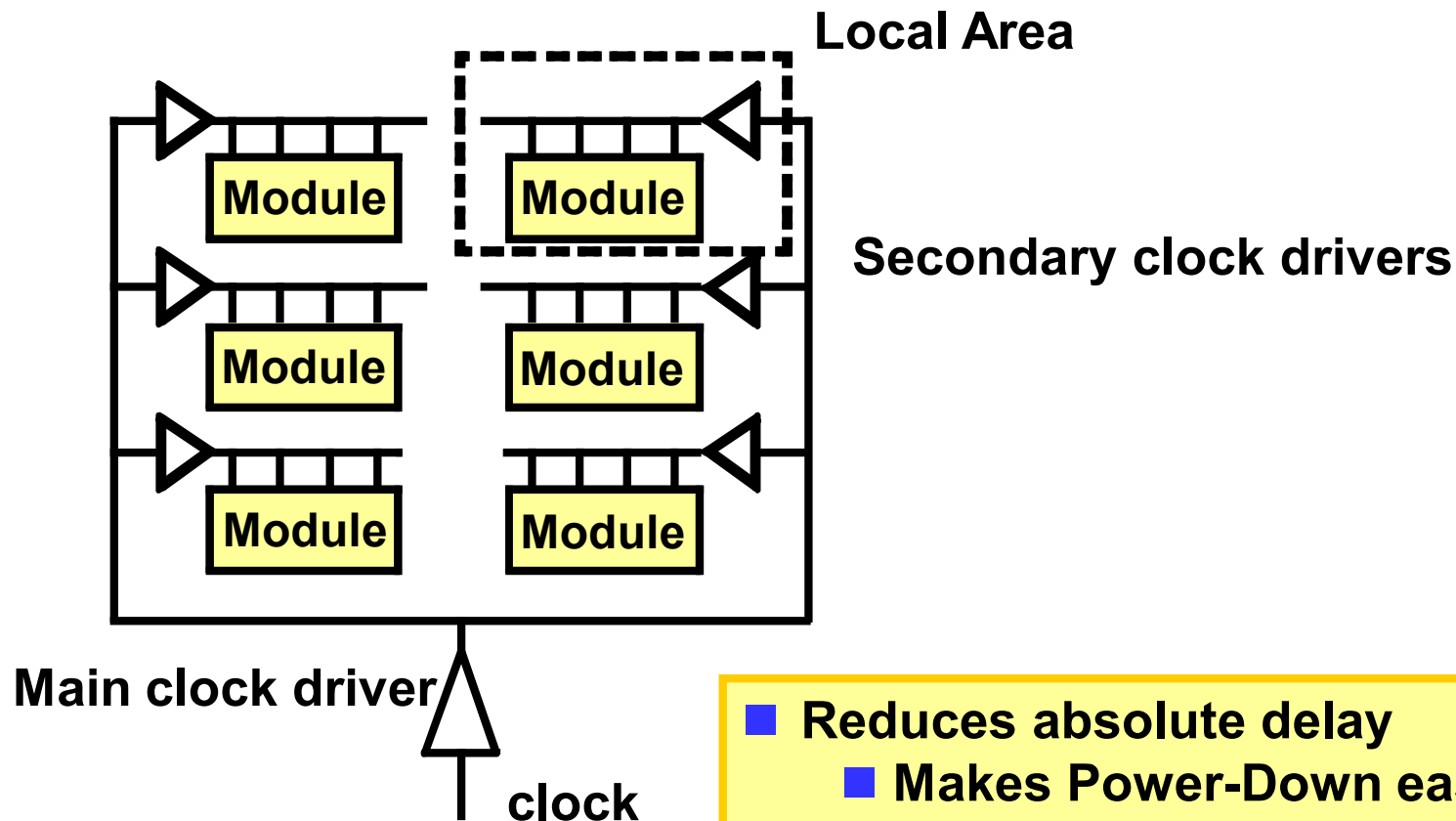
H-tree Clock Network



- All blocks equidistant from clock source \Rightarrow **zero (relative) skew**
- **Sub blocks** should be small enough to ignore intra-block skew
- In practice perfect H-tree shape **not realizable**

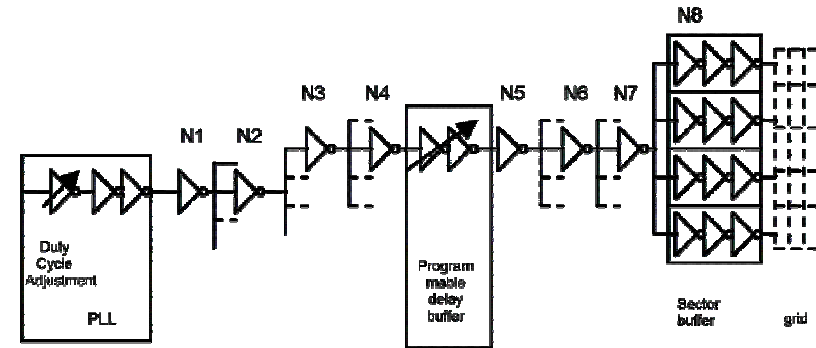
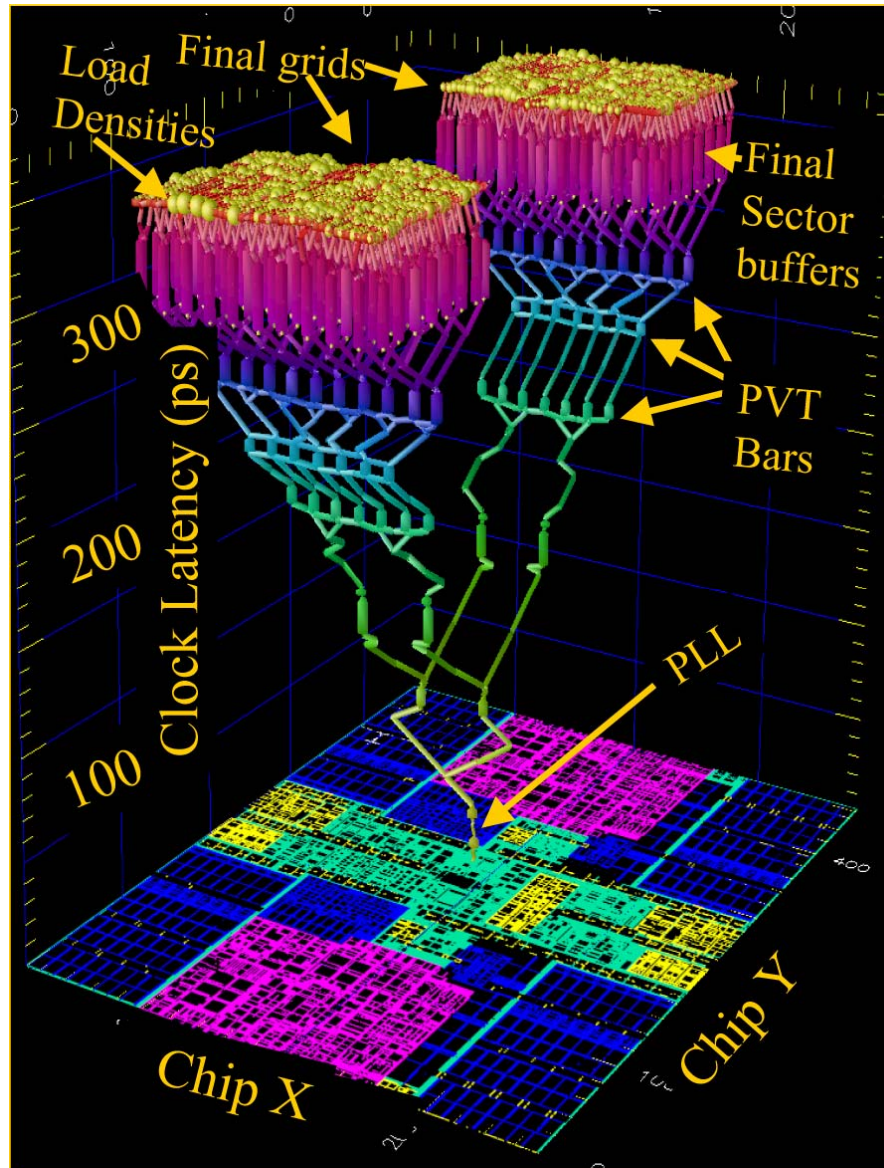
Observe: Only Relative Skew Is Important

Clock Network with Distributed Buffering



- Reduces absolute delay
 - Makes Power-Down easier
 - Easier of-chip communication
- Sensitive to variations in Buffer Delay

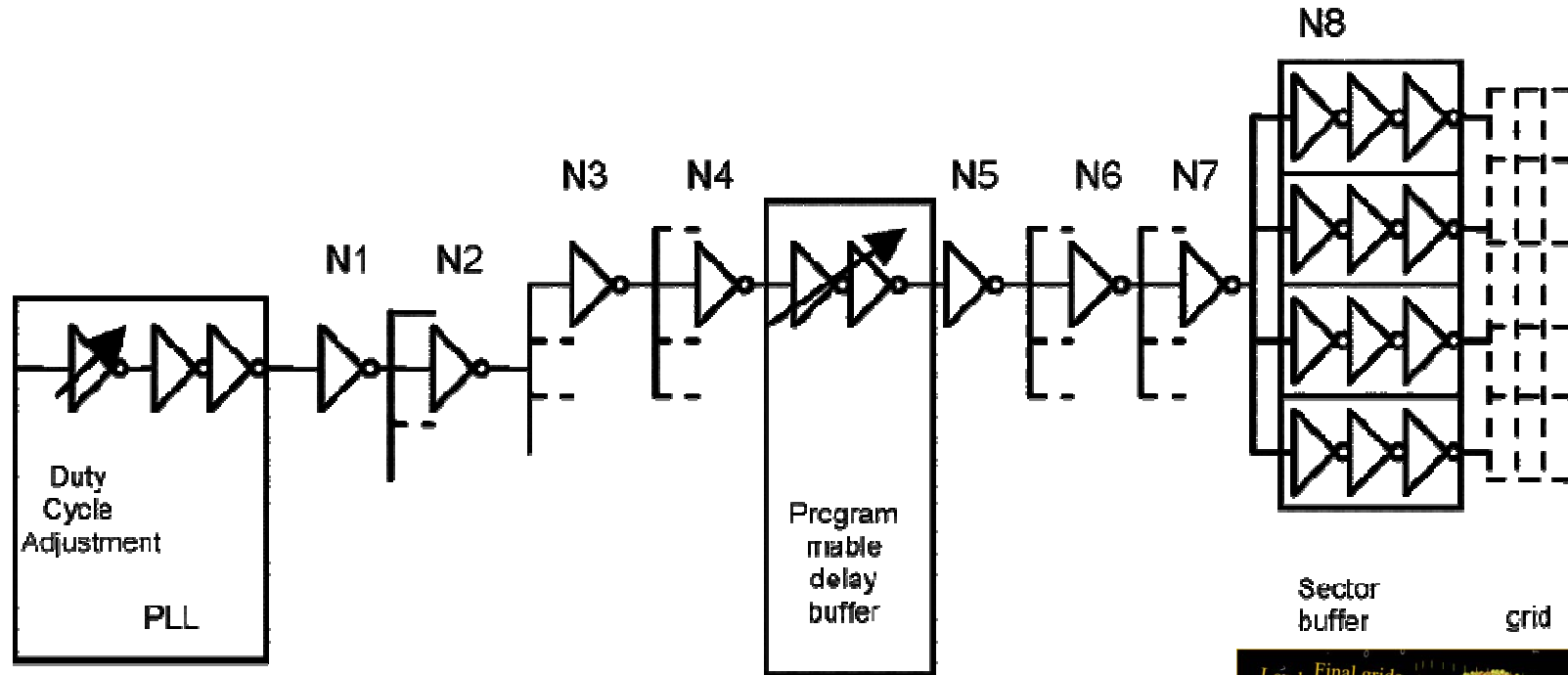
Power6 Clock Distribution



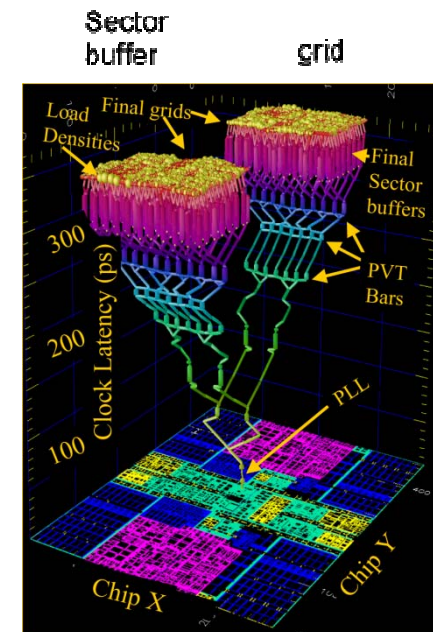
■ Latency ~ cycle time

friedrich, isscc 2007

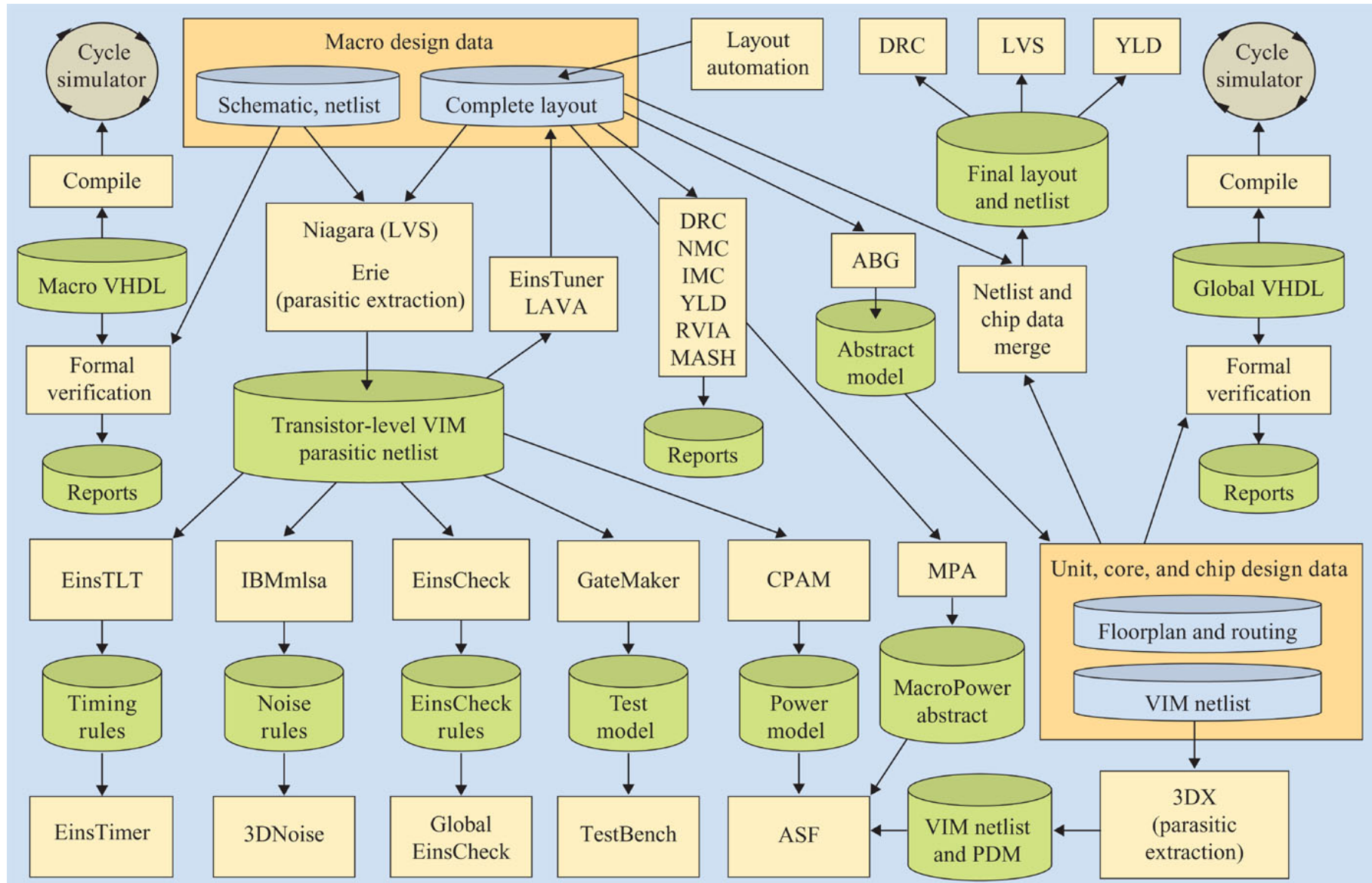
Power6 Clock Distribution



stolt, jssc 2008



IBM Power6 Physical Design Flow



berridge, ibmjrd 2007

Timing Design.

- **Clocking Scheme is important design decision**
- **Influences**
 - **Power**
 - **Robustness**
 - **Ease of design, design time**
 - **Performance**
 - **Area, shape of floor plan**
- **Needs to be planned early in design phase**
- **But is becoming design bottle neck nevertheless**
 - **Clock frequencies increase**
 - **Die sizes increase**
 - **Clock skew significant fraction of T_{clk}**
- **Alternatives**
 - **Asynchronous or self-timed**

Not in this course



Summary

- **Timing Design Background and Motivation**
 - **Delay variations, impact**
 - **Sequential circuits, synchronous design**
 - **Pipelining, metrics reminder**
- **The Clock Skew Problem**
- **Controlling Clock Skew**
- **Case Study**

**Got basic appreciation of some
system level design issues?**