

Resit exam EE2S31 SIGNAL PROCESSING 16 July 2025 13:30–16:30

Closed book; two sides of one A4 with handwritten notes permitted. No other tools except a basic pocket calculator permitted. **Note the attached tables!**

This exam consists of five questions (30 points). Answer in Dutch or English. Make clear in your answer how you reach the final result; the road to the answer is very important. Write your name and student number on each sheet.

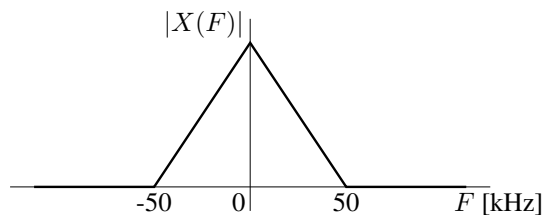
Question 1 (5 points)

An audio signal $x_a(t)$ is sampled at 40 kHz such that we obtain a sequence $x[n] = x_a(nT)$. We take samples during 2.5 seconds. The signal has to be filtered by an FIR filter $h[n]$ with 1024 coefficients.

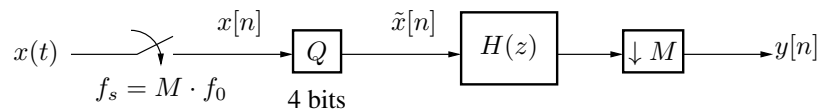
- What is the highest admissible frequency in the signal $x_a(t)$?
- How many multiplications are needed to apply the filter to the data $x[n]$, using a direct implementation of the convolution? (Ignore side effects in this calculation.)
- We would like to use the FFT to reduce the number of operations. Following the overlap-add method, describe in detail how the convolution can be implemented using the FFT. Also give a block scheme.
- How many multiplications are needed now? [Assume that the FFT of order N has a complexity of $N \log_2(N)$.]

Question 2 (9 points)

A signal $x(t)$ has an amplitude spectrum schematically shown as follows:



To sample $x(t)$, an oversampling AD converter operates at $M = 256$ times the desired sampling rate $f_0 = 100$ kHz, and quantizes samples at 4 bits. Digitally, the sample rate is reduced by a factor $M = 256$. See figure:



$H(z)$ is a lowpass filter given by $H(z) = 1 + z^{-1} + \dots + z^{-(M-1)} = \frac{1 - z^{-M}}{1 - z^{-1}}$.

- Draw the amplitude spectrum $|H(e^{j\omega})|$. (Clearly label the frequency axis. For illustration purposes, you may consider a small M .)

In this plot, what is the location (value of ω) of the first zero of the transfer function?

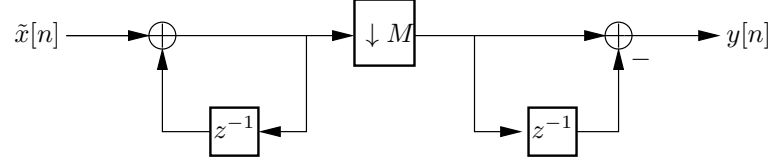
- What is the role of this filter in the context of the oversampling ADC architecture?

If it was an ideal filter, what would be its specification?

- (c) What is the effect of this filter on the quantization noise?
- (d) Draw amplitude spectra for the signals $x[n]$, $\tilde{x}[n]$, and $y[n]$. Label the frequency axis both in terms of ω [rad] and the corresponding original frequencies F [kHz].
- (e) As usual, we model the effect of the quantization as additive white noise, with a uniform distribution. Its variance is $\sigma_e^2 = \Delta^2/12$ with $\Delta = R/2^{B+1}$ where R is the range of the quantizer and $B = 4$ is the number of bits. You may consider $R = 1$.

How many bits accuracy do you expect at the output? (Give a derivation.)

- (f) An efficient implementation of the filter, in combination with the downsampler, is as follows:



Prove that this implementation indeed results in the desired response.

(*Hint*: recall the “noble identities”.)

Question 3 (7 points)

The joint probability density function of two variables X and Y is given by

$$f_{X,Y}(x,y) = \begin{cases} c e^{-2x} e^{-3y} & \text{for } 0 \leq x \leq y \leq \infty \\ 0 & \text{otherwise.} \end{cases}$$

- (a) Calculate the value of constant c .
- (b) Calculate the probability $P[X > 3]$.
- (c) Show that the marginal pdf $f_X(x)$ equals

$$f_X(x) = \frac{1}{3} c e^{-5x}, \quad x \geq 0.$$

- (d) Use the Chebyshev inequality to find an estimate for $P[X > 3]$.
- (e) Calculate the conditional pdf $f_{X|Y}(x|y)$ and the maximum a posteriori estimator $\hat{X}_{MAP}(Y)$.
- (f) Argue whether or not X and Y are independent.

Question 4 (6 points)

We consider the non-stationary stochastic process $X(t)$

$$X(t) = \begin{cases} At^2 & \text{for } t \geq 0 \\ 0 & \text{for } t < 0 \end{cases}$$

where A is a random variable with the following uniform distribution:

$$f_A(a) = \begin{cases} c & \text{for } 0 \leq a \leq 3 \\ 0 & \text{otherwise} \end{cases}$$

- (a) Plot three different realizations of this process.
- (b) Characterize this process: (1) Is it continuous-value or discrete-value? (2) Is it continuous-time or discrete-time? (3) Is it stationary?
- (c) Specify the pdf $f_{X(t)}(x)$ and determine the value of the constant c .
- (d) Calculate the expected value $E[X(t)]$.
- (e) Calculate the autocorrelation function $R_X(t, \tau)$.

Question 5 (3 points)

We consider an LTI system with input process $X(t)$, output process $Y(t)$, and impulse response $h(t)$ given by

$$h(t) = \begin{cases} 4e^{-2t} & \text{for } t \geq 0 \\ 0 & \text{otherwise.} \end{cases}$$

The input process $X(t)$ is WSS, zero mean, uncorrelated with variance σ_X^2 .

- (a) Calculate the autocorrelation function $R_Y(\tau)$ of the output.
- (b) Calculate the power spectral density $S_Y(f)$ of the output.

Tables from Stochastic Processes, Appendix A

Exponential (λ)

For $\lambda > 0$,

$$f_X(x) = \begin{cases} \lambda e^{-\lambda x} & x \geq 0 \\ 0 & \text{otherwise} \end{cases} \quad \phi_X(s) = \frac{\lambda}{\lambda - s}$$

$$E[X] = 1/\lambda$$

$$\text{Var}[X] = 1/\lambda^2$$

Uniform (a, b)

For constants $a < b$,

$$f_X(x) = \begin{cases} \frac{1}{b-a} & a < x < b \\ 0 & \text{otherwise} \end{cases} \quad \phi_X(s) = \frac{e^{bs} - e^{as}}{s(b-a)}$$

$$E[X] = \frac{a+b}{2}$$

$$\text{Var}[X] = \frac{(b-a)^2}{12}$$

Gaussian (μ, σ)

For constants $\sigma > 0$, $-\infty < \mu < \infty$,

$$f_X(x) = \frac{e^{-(x-\mu)^2/2\sigma^2}}{\sigma\sqrt{2\pi}} \quad \phi_X(s) = e^{s\mu + s^2\sigma^2/2}$$

$$E[X] = \mu$$

$$\text{Var}[X] = \sigma^2$$

Tables from Stochastic Processes (R.D. Yates and D.J. Goodman):

Time function	Fourier Transform
$\delta(\tau)$	1
1	$\delta(f)$
$\delta(\tau - \tau_0)$	$e^{-j2\pi f\tau_0}$
$u(\tau)$	$\frac{1}{2}\delta(f) + \frac{1}{j2\pi f}$
$e^{j2\pi f_0\tau}$	$\delta(f - f_0)$
$\cos 2\pi f_0\tau$	$\frac{1}{2}\delta(f - f_0) + \frac{1}{2}\delta(f + f_0)$
$\sin 2\pi f_0\tau$	$\frac{1}{2j}\delta(f - f_0) - \frac{1}{2j}\delta(f + f_0)$
$ae^{-a\tau}u(\tau)$	$\frac{a}{a + j2\pi f}$
$ae^{-a \tau }$	$\frac{2a^2}{a^2 + (2\pi f)^2}$
$ae^{-\pi a^2\tau^2}$	$e^{-\pi f^2/a^2}$
$\text{rect}(\tau/T)$	$T \text{sinc}(fT)$
$\text{sinc}(2W\tau)$	$\frac{1}{2W} \text{rect}(\frac{f}{2W})$

Note that a is a positive constant and that the rectangle and sinc functions are defined as

$$\text{rect}(x) = \begin{cases} 1 & |x| < 1/2, \\ 0 & \text{otherwise,} \end{cases}$$

$$\text{sinc}(x) = \frac{\sin(\pi x)}{\pi x}.$$

Table 1 Fourier transform pairs of common signals.

Time function	Fourier Transform
$g(\tau - \tau_0)$	$G(f)e^{-j2\pi f\tau_0}$
$g(\tau)e^{j2\pi f_0\tau}$	$G(f - f_0)$
$g(-\tau)$	$G^*(f)$
$\frac{dg(\tau)}{d\tau}$	$j2\pi fG(f)$
$\int_{-\infty}^{\tau} g(v) dv$	$\frac{G(f)}{j2\pi f} + \frac{G(0)}{2}\delta(f)$
$\int_{-\infty}^{\tau} h(v)g(\tau - v) dv$	$G(f)H(f)$
$g(t)h(t)$	$\int_{-\infty}^{\infty} H(f')G(f - f') df'$

Table 2 Properties of the Fourier transform.