Delft University of Technology Faculty of Electrical Engineering, Mathematics and Computer Science

EE2S11 SIGNALS AND SYSTEMS

<u>Part 1</u>, 13 December 2018, 13:30 - 15:30

Closed book; two sides of one A4 page with handwritten notes permitted. Graphic calculators not permitted.

This exam has four questions (38 points)

Question 1 (10 points)

Evaluate the following integrals:

a)
$$\int_{t=-4}^{4} t^2 \left[\delta(t+2) + \delta(t) + \delta(t-5) \right] dt$$

b)
$$\int_{t=-4}^{4} (t^2+2) \left[\delta(t) + 3\delta(t-2)\right] dt$$

c)
$$\int_{t=-4}^{4} t^2 \delta'(t-2) \,\mathrm{d}t$$

The signal y(t) satisfies the differential equation

$$4y'(t) + 8y(t) = 12\delta(t)$$
, with $y(0^{-}) = 0$.

- d) Determine $y(0^+)$.
- e) Find a signal z(t) such that z(t) = 0 for t < 0 and $z'(t) = 12\delta(t) 24e^{-2t}u(t)$.

Solution

- a) 4, note that t = 5 does not belong to the integration interval.
- b) 20
- c) -4
- d) $y(0^+) = 3$
- e) $z(t) = 12e^{-2t}u(t)$

Question 2 (8 points)

The action of an LTI system with an input signal x(t) and output signal y(t) is described by the differential equation

$$y''(t) + 4y'(t) + 13y(t) = x(t)$$
 for $t > 0^{-1}$

with initial conditions $y(0^-) = 4$ and $y'(0^-) = 4$.

a) Determine the impulse response h(t) of the system.

The zero-input response $y_{zi}(t)$ of the system can be written as

$$y_{\rm zi}(t) = Ae^{-\alpha t}\cos(\omega t + \varphi)u(t).$$

b) Determine A, α, ω , and φ .

Solution

a) To determine the impulse response, take $x(t) = \delta(t)$ and set the initial conditions to zero. A one-sided Laplace transform gives the transfer function

$$H(s) = \frac{1}{s^2 + 4s + 13} = \frac{1}{3} \frac{3}{(s+2)^2 + 3^2}.$$

The inverse Laplace transform of this transfer function is

$$h(t) = \frac{1}{3}e^{-2t}\sin(3t)u(t).$$

b) Set the input signal to zero x(t) = 0, apply the one-sided Laplace transform to the differential equation, and take the initial conditions into account to obtain

$$Y_{\rm zi}(s) = \frac{4s+20}{s^2+4s+13} = \frac{C}{s+2-3j} + \frac{C^*}{s+2+3j}$$

with $C = 2(1 - j) = 2\sqrt{2}e^{-j\pi/4}$. An inverse Laplace transform now gives

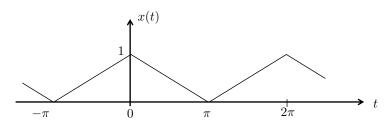
$$y_{\rm zi}(t) = 2\sqrt{2}e^{-2t} \left[e^{j(3t-\pi/4)} + e^{-j(3t-\pi/4)} \right] u(t)$$

= $4\sqrt{2}e^{-2t} \cos(3t-\pi/4)u(t).$

We find that $A = 4\sqrt{2}$, $\alpha = 2$, $\omega = 3$, and $\varphi = -\pi/4$.

Question 3 (10 points)

Consider the real-valued continuous-time periodic signal x(t) depicted below:



The Fourier series expansion of x(t) is given by

$$x(t) = \sum_{k=-\infty}^{\infty} X_k e^{jk\Omega_0 t}, \quad t \in [t_0, t_0 + T_0), \qquad X_k = \frac{1}{T_0} \int_{t_0}^{t_0 + T_0} x(t) e^{-jk\Omega_0 t} dt, \quad k \in \mathbb{Z}.$$
 (1)

- a) Without explicitly computing the Fourier series, what can you say about the spectrum of x(t): Is it discrete or continuous, is it real, imaginary of complex-valued, and do we have symmetry in the spectrum? Motivate your answer.
- b) Compute the Fourier series expansion of x(t) using (1).
- c) Compute the Fourier coefficients using the Laplace transform.
- d) Give a sketch of the magnitude and phase spectrum of x(t).

Assume the signal x(t) is the input of an LTI system of which the output is $y(t) = \pi \frac{dx(t)}{dt}$.

- e) Compute the Fourier series expansion of y(t).
- f) What is the order of decay of both spectra? Explain which one decays fastest and why.

Solution

- a) Since x is a periodic signals, the spectrum is a line spectrum. Moreover, since x is even symmetric, the spectrum is real and since x is real valued, the spectrum is conjugate symmetric. That is, the magnitude spectrum is even symmetric and the phase spectrum is odd symmetric.
- b) Since x is even symmetric, we have $(\Omega_0 = 1)$

$$\int_{-\pi}^{\pi} x(t)e^{-jkt}dt = \int_{-\pi}^{\pi} x(t)(\cos(kt) - j\sin(kt))dt = \int_{-\pi}^{\pi} x(t)\cos(kt)dt.$$

Hence,

$$X_{k} = \frac{1}{\pi} \int_{0}^{\pi} (1 - \frac{t}{\pi}) \cos(kt) dt = \underbrace{\frac{1}{\pi} \int_{0}^{\pi} \cos(kt) dt}_{I} - \underbrace{\frac{1}{\pi} \int_{0}^{\pi} \frac{t}{\pi} \cos(kt) dt}_{II}.$$

 $k \neq 0$:

$$\frac{1}{\pi} \int_0^\pi \cos(kt) dt = -\frac{1}{\pi k} \sin(kt) \Big|_0^\pi = 0.$$

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$$-\frac{1}{\pi^2} \int_0^\pi t \cos(kt) dt = \frac{1}{\pi^2 k} t \sin(kt) \Big|_0^\pi - \frac{1}{\pi^2 k} \int_0^\pi \sin(kt) dt = \frac{1}{\pi^2 k} \sin(kt) \int_0^\pi \sin(kt) dt = \frac{1}{\pi^2$$

$$-\frac{1}{\pi^2} \int_0^{\pi} t \cos(kt) dt = \frac{1}{\pi^2 k} t \sin(kt) \Big|_0^{\pi} - \frac{1}{\pi^2 k} \int_0^{\pi} \sin(kt) dt$$

$$= 0 - \frac{1}{(\pi k)^2} \cos(kt) \Big|_0^{\pi} = \frac{1}{(\pi k)^2} \left(\left(1 - (-1)^k \right) \right).$$

k = 0:

$$\begin{split} \kappa &= 0. \\ I : \\ I : \\ II : \\ II : \\ \end{bmatrix} &- \frac{1}{\pi^2} \int_0^{\pi} t dt = -\frac{1}{2\pi^2} t^2 \Big|_0^{\pi} = -\frac{1}{2}, \end{split}$$

II: $X_0 = \frac{1}{2}$. Note that X_k is indeed real.

c) We have that $x(t) = \frac{1}{\pi}r(t+\pi) - \frac{2}{\pi}r(t) + \frac{1}{\pi}r(t-\pi)$. Applying the Laplace transform yields $X(s) = \frac{1}{\pi s^2} \left(e^{s\pi} + e^{-s\pi} - 2\right).$

so that the Fourier coefficients are given by $(k \neq 0)$,

$$X_k = \frac{1}{2\pi} X(s) \bigg|_{s=jk} = \frac{-1}{2(\pi k)^2} \left(e^{jk\pi} + e^{-jk\pi} - 2 \right) = \frac{1}{(\pi k)^2} \left(\left(1 - (-1)^k \right) \right).$$

For k = 0 we note that $\lim_{s \to 0} X(s) = \pi$, so that $X_0 = \frac{1}{2}$.

d) The magnitude and phase spectrum $|X_k|$ and $\angle X_k$ are:

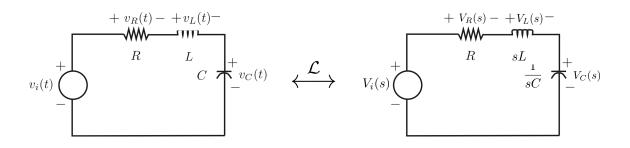
e) Since $y(t) = \pi \frac{dx(t)}{dt}$, we have

$$Y_k = jk\pi X_k = \begin{cases} 0, & k \text{ even,} \\ \frac{2j}{\pi k}, & k \text{ odd.} \end{cases}$$

f) The decay of X_k is $\mathcal{O}(1/k^2)$ since x has is continuous but not continuously differentiable. The decay of Y_k is slower $(\mathcal{O}(1/k))$ since y has discontinuities (square wave).

Question 4 (10 points)

Consider the RLC circuit depicted below:



Let $H_L(s)$ denote the transfer function of the (input) voltage source to the (output) voltage across the inductor,

$$H_L(s) = \frac{V_L(s)}{V_i(s)}, \quad s \in \text{ROC}.$$

a) Give an expression for $H_L(s)$ in terms of R, L and C.

For simplicity, now assume that R = L = C = 1.

- b) Determine the poles and zeros of the system and draw them in the complex s-plane. Is the system BIBO stable? Motivate your answer.
- c) Give an expression for the frequency, magnitude and phase response of the system.
- d) Sketch the magnitude and phase response and indicate the values of $|H_L(j\Omega)|$ and $\angle H_L(j\Omega)$ for the (angular) frequencies $\Omega = 0$ and $\Omega = \pm \infty$.
- e) Suppose we consider the transfer to the output across the resistor or capacitor, given by $H_R(s)$ and $H_C(s)$, respectively. Argue whether the corresponding frequency responses are low-, band- or highpass. Motivate your answer by considering the pole-zero locations of the transfer functions, and indicate how they differ from the pole-zero locations of $H_L(s)$.

Solution

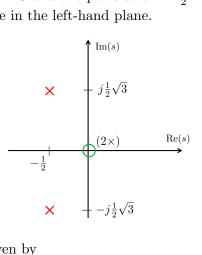
a) We have

$$H_L(s) = \frac{s^2 L C}{s^2 L C + s R C + 1}.$$

b)

$$H(s) = \frac{s^2}{s^2 + s + 1} = \frac{s^2}{(s + \frac{1}{2}(1 - j\sqrt{3}))(s + \frac{1}{2}(1 + j\sqrt{3}))}.$$

Hence, we have two zero at s = 0 and two poles at $s = -\frac{1}{2} \pm j\frac{1}{2}\sqrt{3}$. The causal system is BIBO stable since all poles lie in the left-hand plane.



b) The frequency response is given by

$$H(\Omega) = H(s) \bigg|_{s=j\Omega} = \frac{-\Omega^2}{1 - \Omega^2 + j\Omega}$$

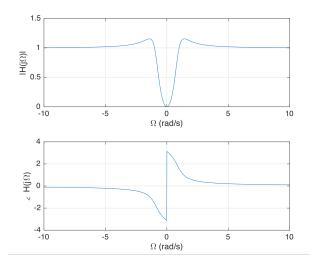
Hence, the magnitude response is given by

$$|H(\Omega)| = \frac{\Omega^2}{\sqrt{(1 - \Omega^2)^2 + \Omega^2}}$$

and the phase response by

$$\angle H(\Omega) = \pi - \tan^{-1}\left(\frac{\Omega}{1-\Omega^2}\right).$$

c) We have |H(0)| = 0 and $|H(\pm \infty)| = 1$, Since we have two zeros at s = 0, we get a jump of 2π radians at $\Omega = 0$. Hence, $\angle H(0^+) = \pi$ and $\angle H(0^-) = -\pi$. Moreover, $\angle H(\pm \infty) = 0$.



d) The transfer function H_R and H_C are given by

$$H_R(s) = \frac{s}{s^2 + s + 1}, \quad H_C(s) = \frac{1}{s^2 + s + 1}.$$

They differ from H_L is the number of zeros (at s = 0). Hence, removing one zero from $H_L(s)$ will result in a band-pass filter, since there is still one zero left at s = 0 but $|H_R(\pm \infty)| = 0$. If we remove both zeros, we obtain a low-pass filter since in that case |H(0)| = 1 and certainly $|H_R(\pm \infty)| = 0$.